

Review Article

Efficient Coding Schemes for Fault-Tolerant Parallel Filters: A Survey

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ABSTRACT

The trends in computing processor technology are shifting towards multicore architectures achieved through miniaturization, enabling the integration of numerous processors within a confined chip area. However, this downsizing has led to a notable rise in soft errors, where a single bit flip can significantly impact the output of a computing system. Consequently, this phenomenon detrimentally affects the performance of applications running on such systems. The scaling of CMOS technology introduces fresh challenges for designers in the form of novel failure modes, including long-term reliability issues and random failures induced by particle strikes. Research indicates that soft errors are increasingly emerging as the foremost contributor to device reliability failures. Consequently, the implementation of soft error mitigation techniques is being widely adopted to address these reliability concerns. As the uptake of these mitigation strategies grows, the associated concerns regarding the incurred area and performance overhead also become pertinent. This research endeavours to tackle the predicament of furnishing cost-effective soft error mitigation solutions.

KEYWORDS

Coding, Parallel filters, soft errors.

1. INTRODUCTION

Technology scaling has enabled us to keep pace with the power, performance, area and functionality requirements of electronic circuits. Along with the advantages, it has also given challenges due to increased leakage current, reliability failures, etc [2]. Reliability failures include systematic failures due to the aging effects of silicon structures caused by Negative Bias Temperature Instability (NBTI) and Hot Carrier Injection (HCI) [3] and random failures due to atmospheric particle strikes, called as soft errors [4]. The contribution of particle strike induced failures to the overall device fail rate is more than ten times than that due to a hard reliability fail [5]. This highlights the importance of the requirement of soft error mitigation in safety critical systems.

Initially soft errors were a concern only for safety critical applications. But with the scaling of technology, soft errors are becoming pertinent even for electronic devices in consumer market space. Due to the prohibitive cost associated with the design, manufacturing and other collaterals required for integrated circuits, very often devices designed with strong emphasis in one market segment will find use in another, e.g. products reused across catalog (consumer) and automotive markets. Hence the reliability requirements pose the dual challenges of meeting the strict reliability goals required for one market and at the same time adhering to the affordable costs driving the other

market. This makes it increasingly important to reduce the overall cost of implementation of methodologies adopted and incorporated into circuits for soft error mitigation. This implies less area overhead, less impact on performance and ease of implementation. In addition, from a reliability perspective there are also requirements regarding the error detection latency, time required to roll back to a known good state etc.

Since their inception, control systems have been an enabling technology. Control systems were introduced during the industrial revolution with devices like the James Watt fly ball governor, [2]. Over the past 40 years, the developments in analog and digital electronics have resulted in dramatic increases in the computational power of microcomputers and microcontrollers. These developments provided for the implementation of advanced control techniques. These advanced control techniques enabled the successful development of high performance applications such as:

- Guidance and control systems for aerospace vehicles such as commercial aircraft, guided missiles, advanced fighter aircraft, launch vehicles and satellites. These control systems provide stability and tracking in the presence of large environmental and system uncertainties.
- Control systems in the manufacturing industries from automotive to integrated circuits, which are associated with computer-controlled machines, provide the precise

positioning and assembly required for high-quality, high-yield fabrication of components and products.

- Industrial process control systems, particularly in the hydrocarbon and chemical processing industries, maintain high product quality. Product quality is maintained by monitoring thousands of sensors signals and making corresponding adjustments to hundreds of valves, heaters, pumps and other actuators.
- Control of communication systems such as the telephone system, cell phones, and the Internet are especially pervasive. These control systems regulate the signal power levels in transmitters and repeaters, manage packet buffers in network routing equipment and provide adaptive noise cancelation to respond to varying transmission line characteristic. Control systems have reached a high level of theoretical development and there exists a myriad of applications. However, the development of new sensors and actuators for old and new applications continues. Therefore, the demand for new theoretical concepts and approaches, to handle increasingly complex applications remains high.

Challenges of Technology Scaling

Continued evolution of technology in the semiconductor domain has led to smaller area, higher operating frequencies and lower voltage levels. This has helped us in integrating more and more complex functions into a single System-on-Chip (SoC). In addition to these benefits, the evolution of technology provided an increased set of design challenges required to address the permanent failures and transient failures which came up with technology scaling. Permanent failures can be classified as either extrinsic or intrinsic. Extrinsic faults caused by manufacturing defects result in early failure of devices called as infant mortality. Intrinsic faults arise due to degradation phenomena which result in the wear-out of silicon chips.

The “bathtub curve” shown in Figure 1.1 depicts the life time of a device. During the initial part of the device operation, extrinsic faults due to defects induced during manufacturing process lead to high failure rate. Burn-in process is used to eliminate this. The next phase is the flat portion of the curve which indicates the useful lifetime of the device. During this stage, the failures are due to radiation induced transient faults. Finally near the end of a chip’s lifetime, wear-out mechanisms cause an increase in the failure rate.

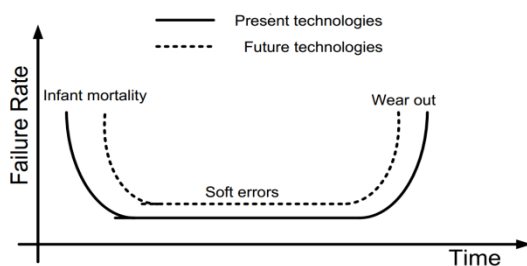


Figure 1.1 The bathtub curve

The dashed line indicates the variation in failure rates with technology scaling. With technology scaling, infant

mortality is becoming more prevalent. This makes it mandatory for devices in new technology nodes to have burn-in test step as a part of the production test flow to screen extrinsic reliability fails. Also, radiation induced failures are on the rise. Effectively, the operational life-span of the device is reduced. Permanent faults and time induced faults must be detected before shipping the device. In contrast, radiation induced transient fault must be taken care in the field by appropriate error detection and correction circuitry.

Wear-out Failure Modes in Future Technologies

Operating life failures in semiconductor devices are caused due to Electromigration, Hot Carrier Injection (HCI) and Negative Bias Temperature Instability (NBTI). This can affect the transistors or electrical wires in the device. These types of faults first give rise to intermittent delay faults and later result in permanent failures.

Soft Error Trends

The initial part of the research on soft errors has mostly concentrated on soft errors of memories and later on other sequential state holding elements. The soft error contribution of combinational logic has been overlooked and not much of research has focussed on this front.

The SER contribution of different logic elements to the overall FIT rate of the circuit. Figure 1.2 shows the observations from this study. It is observed that the contribution of combinational logic to the overall FIT rate is 11%. It is increasing and can no longer be ignored. Shivakumaret. al. [12] also did a detailed study of the SER trends in memories, sequential elements and combinational logic.

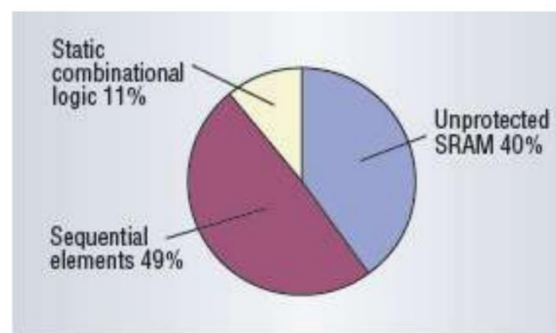


Figure 1.2 Soft error contributions of memory and logic

2. LITERATURE REVIEW

Z. Gao, P. Reviriego, Z. Xu, X. Su, J. Wang and J. A. Maestro, [1] As the complexity of communications and signal processing systems increases, so does the number of blocks or elements that they have. In many cases, some of those elements operate in parallel, performing the same processing on different signals. A typical example of those elements is digital filters. The increase in complexity also poses reliability challenges and creates the need for fault-tolerant implementations. A scheme based on error correction coding has been recently proposed to protect parallel filters. In that scheme, each filter is treated as a bit,

and redundant filters that act as parity check bits are introduced to detect and correct errors. In this brief, the idea of applying coding techniques to protect parallel filters is addressed in a more general way. In particular, it is shown that the fact that filter inputs and outputs are not bits but numbers enables a more efficient protection. This reduces the protection overhead and makes the number of redundant filters independent of the number of parallel filters. The proposed scheme is first described and then illustrated with two case studies. Finally, both the effectiveness in protecting against errors and the cost are evaluated for a field-programmable gate array implementation.

M. Nicolaidis, [2] Innanometric technologies, circuits are increasingly sensitive to various kinds of perturbations. Soft errors, a concern for space applications in the past, became a reliability issue at ground level. Alpha particles and atmospheric neutrons induce single-event upsets (SEU), affecting memory cells, latches, and flip-flops, and single-event transients (SET), initiated in the combinational logic and captured by the latches and flip-flops associated to the outputs of this logic. To face this challenge, a designer must dispose a variety of soft error mitigation schemes adapted to various circuit structures, design architectures, and design constraints. In this paper, authors describe various SEU and SET mitigation schemes that could help the designer meet her or his goals.

A. L. N. Reddy and P. Banerjee,[3] The increasing demands for high-performance signal processing along with the availability of inexpensive high-performance processors have results in numerous proposals for special-purpose array processors for signal processing applications. A functional-level concurrent error-detection scheme is presented for such VLSI signal processing architectures as those proposed for the FFT and QR factorization. Some basic properties involved in such computations are used to check the correctness of the computed output values. This fault-detection scheme is shown to be applicable to a class of problems rather than a particular problem, unlike the earlier algorithm-based error-detection techniques. The effects of roundoff/truncation errors due to finite-precision arithmetic are evaluated. It is shown that the error coverage is high with large word sizes.

S. Pontarelli, G. C. Cardarilli, M. Re and A. Salsano,[4] In this paper, the design of a finite impulse response (FIR) filter with fault tolerant capabilities based on the residue number system is analyzed. Differently from other approaches that use RNS, the filter implementation is fault tolerant not only with respect to a fault inside the RNS moduli, but also in the reverse converter. An architecture allowing fault masking in the overall RNS FIR filter is presented. It avoids the use of a trivial triple modular redundancy (TMR) to protect the blocks that performs the final stages of the RNS based FIR computation.

Byonghyo Shim and N. R. Shanbhag, [5] In this paper, authors present energy-efficient soft error-tolerant techniques for digital signal processing (DSP) systems. The proposed technique, referred to as algorithmic soft error-tolerance (ASET), employs low-complexity estimators of a main DSP block to achieve reliable operation in the presence

of soft errors. Three distinct ASET techniques - spatial, temporal and spatiotemporal- are presented. For frequency selective finite-impulse response (FIR) filtering, it is shown that the proposed techniques provide robustness in the presence of soft error rates of up to $P/\text{sub } er/=10/\text{sup } -2/$ and $P/\text{sub } er/=10/\text{sup } -3/$ in a single-event upset scenario. The power dissipation of the proposed techniques ranges from 1.1 X to 1.7 X (spatial ASET) and 1.05 X to 1.17 X (spatio-temporal and temporal ASET) when the desired signal-to-noise ratio $\text{SNR}/\text{sub } des/=25$ dB. In comparison, the power dissipation of the commonly employed triple modular redundancy technique is 2.9 X.

Z. Gao, W. Yang, X. Chen, M. Zhao and J. Wang,[6] Relative to the Triple Modular Redundancy (TMR) scheme, the arithmetic residue codes based fault-tolerant DSP design consumes much less resources. However, the price for the low resource consumption is the fault missing problem. The basic tradeoff is that, smaller modulus used for the fault checking consumes fewer resources, but the fault missing rate is higher. The relationship between the value of modulus and the fault missing rate is analyzed theoretically in this paper for fault-tolerant FIR filter design, and the results are verified by FPGA implemented fault injections.

3. PROBLEM IDENTIFICATION

Fault-tolerant parallel filters had been presented in the previous research work. The proposed scheme exploits the linearity of filters to analysis an error correction mechanism. In particular, two redundant filters whose inputs are linear combinations of the original filter inputs are used to detect and locate the errors. The coding of those linear combinations was formulated as a general problem to then show how it can efficiently be implemented. The practical implementation was illustrated with two case studies that were evaluated for an FPGA implementation and compared with a previously technique. That technique relies on the use of ECCs such that each filter is treated as a bit in the ECC.

4. CONCLUSION

In modern VLSI systems are a major reliability concern. These upsets originate from two primary sources: cosmic ray particles occurring in the space environment and alpha particles emitted from the radioactive decay of uranium and thorium impurities located within the chip itself such as the silicon die, interconnects, and ceramic packaging. Soft errors due to SEUs have been a known problem affecting semiconductor memories for quite some time.

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